ELEC3210 Machine Learning and Information Processing for Robotics Fall 2023

Course Description

The real course title should be "Introduction to Mobile Robotics" in Fall 2023. This course gives a comprehensive introduction to mobile robot and autonomous navigation. The goal of this course is to expose students to relevant conceptual knowledges, mathematical foundations and algorithms, and help them to develop real-time software modules for autonomous navigation. Topics to be covered include ROS, locomotion, sensors, SLAM, motion planning and advanced robotics.

■ Platform

All on Convas

Team

Instructor

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Teaching Assistant

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■ Timetable (Tentative)

Lecture	Date	Contents Projects		
L1	04/09	Robotics, Autonomous Mobile Robot (Install Ubuntu & ROS		
L2	06/09	Pose, ROS		
L3	11/09	Localization, Wheeled Locomotion		
L4	13/09	Sensors		
L5	18/09	Iterative Closeset Point P1 - ICP odometry		
L6	20/09	Map Representations		
L7	25/09	Bayes Theorem, Gaussian Distribution		
L8	27/09	Particle Filter and MCL		
	2/10, 4/10	National Day / IROS 2023 Conference		
L9	09/10	Kalman Filter, EKF	P1 Out	
L10	11/10	SLAM and EKF SLAM	P2 - EKF SLAM	

L11	16/10	Fast SLAM with Particle Filter		
L12	18/10	Graph SLAM		
L13	25/10	Place Recognition		
L14	30/10	Advanced Topic – Visual SLAM 1 (TBD)		
L15	01/11	Advanced Topic - Visual SLAM 2	P2 Out	
L16	06/11	Path Planning 1	P3 - Planning	
L17	08/11	Path Planning 2		
L18	13/11	Trajectory Planning – Guest Lecturer by Haokun		
L19	15/11	Advanced Topic – Drones (TBD)		
L20	20/11	Summary and Future Mobile Robots		
L21	22,27/11	Project 3 Time	t 3 Time P3 Out	
	29/11	Study Break		

■ TextBooks (Non Compulsory)

- Siegwart, Roland, Illah Reza Nourbakhsh, and Davide Scaramuzza. Introduction to autonomous mobile robots. MIT press, 2011.
- Thrun, Sebastian. "**Probabilistic robotics**." Communications of the ACM 45.3 (2002): 52-57.

■ Grading Scheme, No midterm or final exams

		Note
Quizz	20%	Randomly conducted in lectures
Homework	30%	Submit after lectures
Project	P1 10%	Online projects
	P2 20%	Linux/C++ Required
	P3 20%	Submit Video & Code & Report