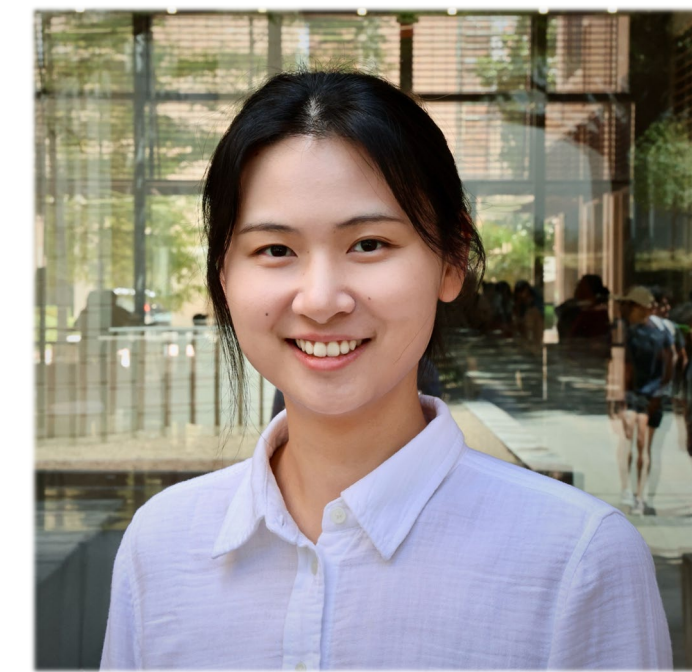


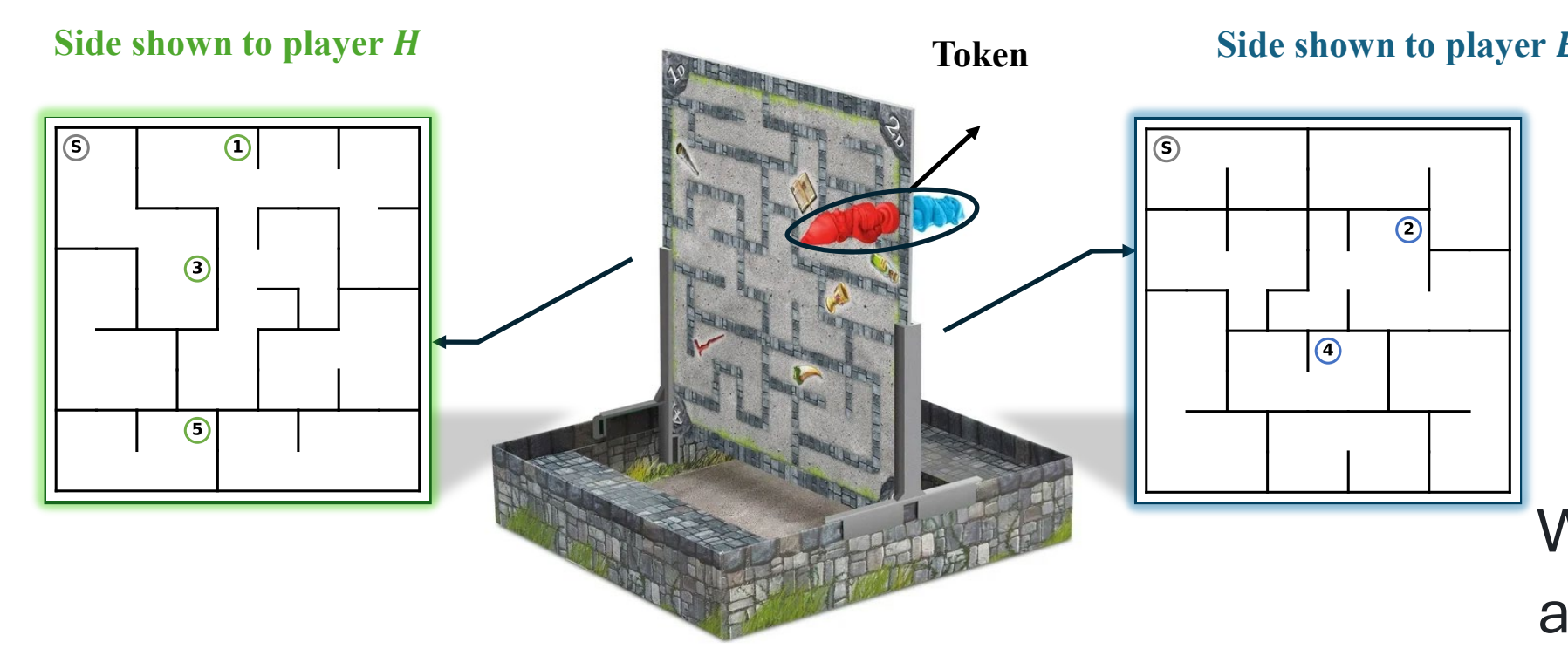


How to enable AI agents to collaborate adaptively with humans under incomplete information?

Coordinate under Incomplete Information

Testbed: Gnomes at Night

Our testbed, Gnomes at Night , is a maze game where two players alternately control a token to achieve a common goal with incomplete information.



Shared-Control Game

A shared-control game where player E and player H collectively controls a token in alternating turns:

$$\Gamma = (\mathcal{S}, s_{init}, s_{final}, \mathcal{A}^E, \mathcal{A}^H, \mathcal{T}^E, \mathcal{T}^H) \text{ where}$$

$\mathcal{S}$ is a finite set of states,

s_{init} is an initial state, s_{final} is a final state,

$\mathcal{A}^i$ is a finite set of actions of player $i \in \{E, H\}$,

$\mathcal{T}^i: \mathcal{S} \times \mathcal{A}^i \rightarrow \mathcal{S}$ is a **private** deterministic transition function of each player $i \in \{E, H\}$.

We augment Γ with a **common** reward function that assigns equal reward to both: $\mathcal{R}: \mathcal{S} \times \cup_i \mathcal{A}^i \rightarrow \mathbb{R}$.

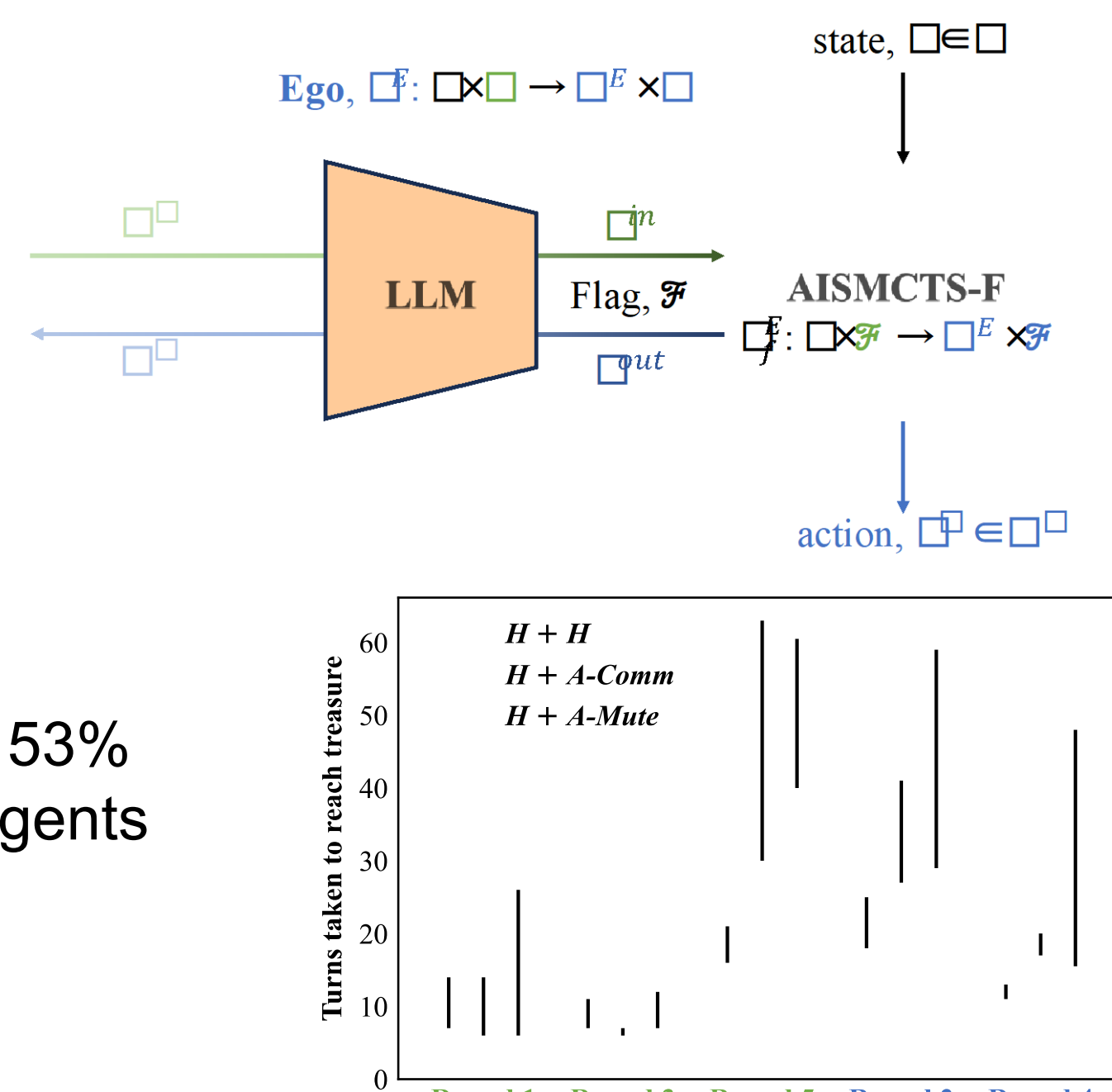
Communication-based Approach

Human-Agent Cooperation in Games under Incomplete Information through Natural Language Communication. IJCAI 2024.

Language module: translates natural language messages into and from a finite set of *flags*, a compact representation defined to capture player intents. (We implement using few shot-prompting with gpt-3.5-turbo.)

Planning module: leverages these flags to compute a policy using an algorithm called *AIMCTS-F* that we introduce.

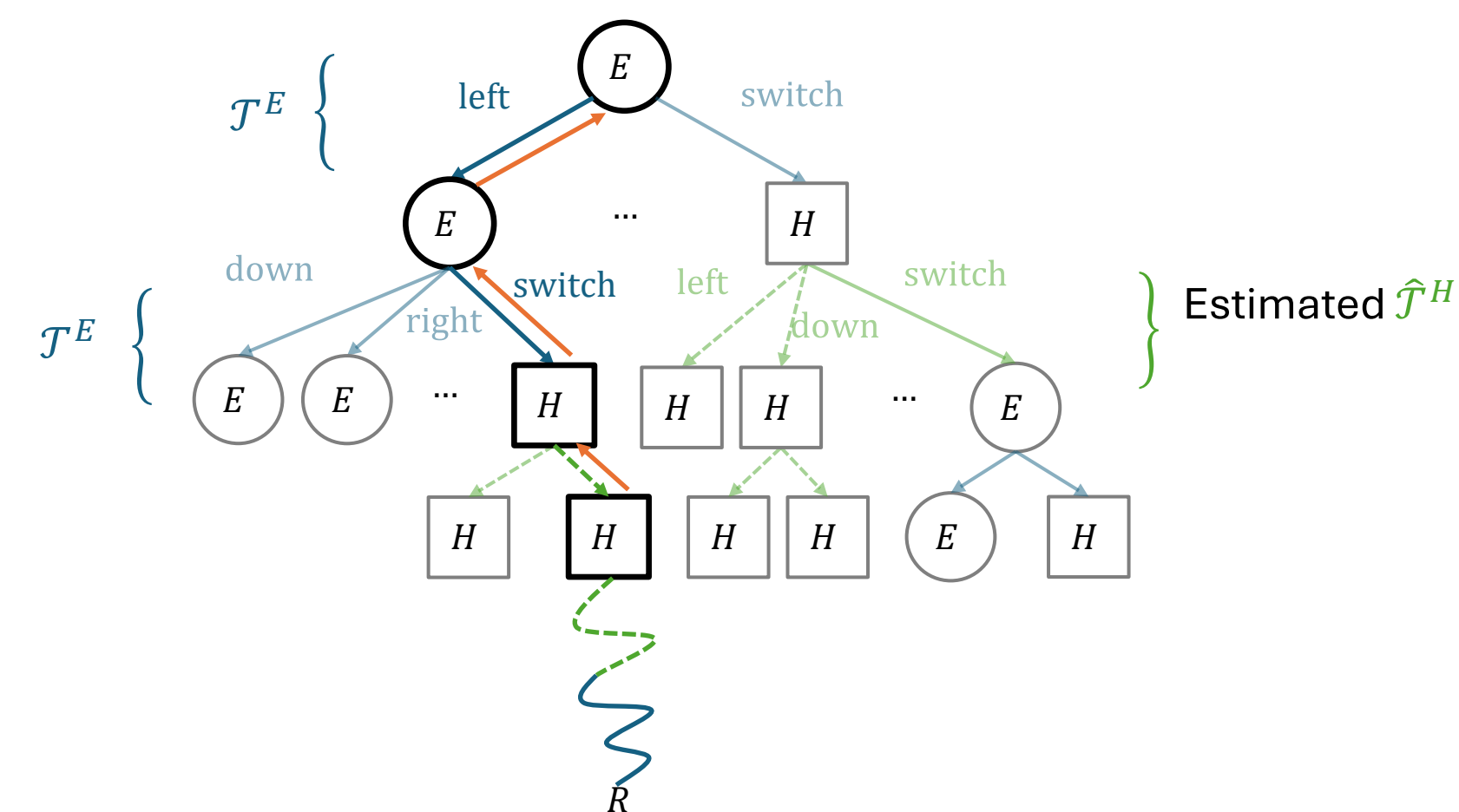
Flags: $\mathcal{F} = \mathcal{A}^H \cup \mathcal{A}^E \cup \{\text{Accept, Reject, Inquiry, None}\}$



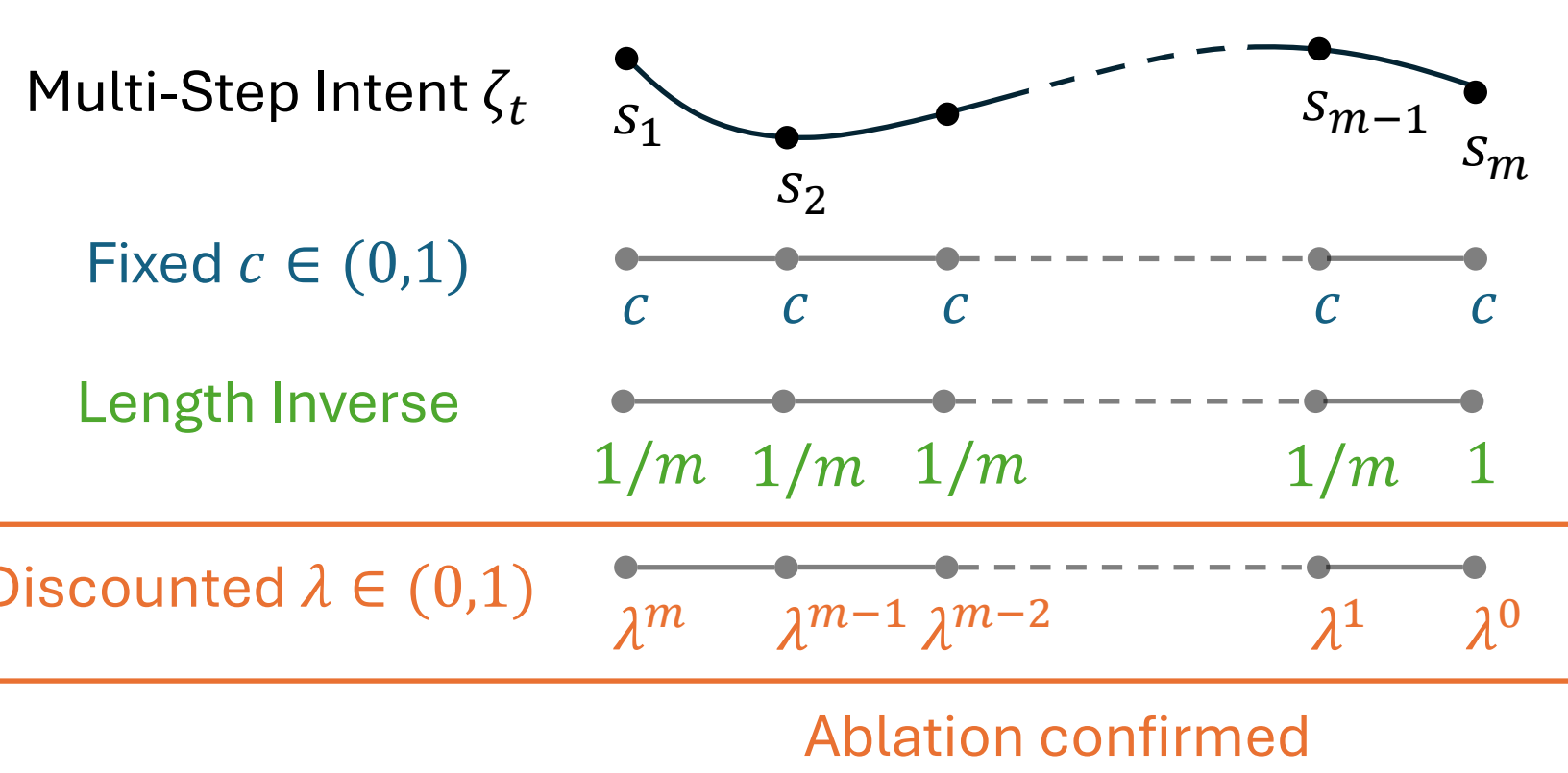
User study. With 150 Prolific participants (mean age = 34.71; 53% female), communication-enabled agents outperformed mute agents in 4 of 5 rounds, requiring significantly fewer turns (ANOVA: $F(2,627) = 10.53, p < .01$; Tukey HSD: $p < .05$)

IntentMCTS

Human-Agent Coordination in Games under Incomplete Information via Multi-Step Intent. AAMAS 2025.



Incorporate multi-step intent via reward augmentation



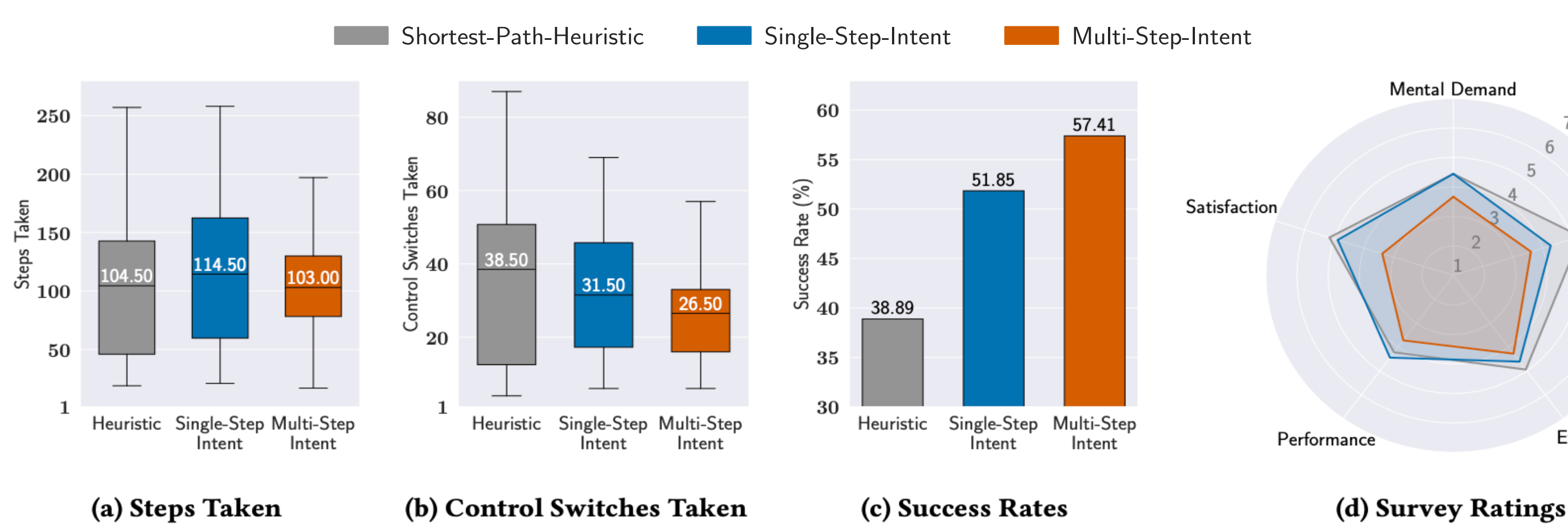
Rollout with current best knowledge (known $\mathcal{T}^E$ & estimated $\hat{\mathcal{T}}^H$ transitions)

$$\begin{aligned} \text{From leaf to root: } N(v) &\leftarrow N(v) + 1 \\ Q(v) &\leftarrow Q(v) + q_{\text{sample}} \end{aligned}$$

Step reward: $r + \gamma [\delta' q'_{\text{sample}} + (1 - \delta') \frac{Q(v)}{N(v)}]$

Transition feasible: future return
Transition infeasible: Current value estimate

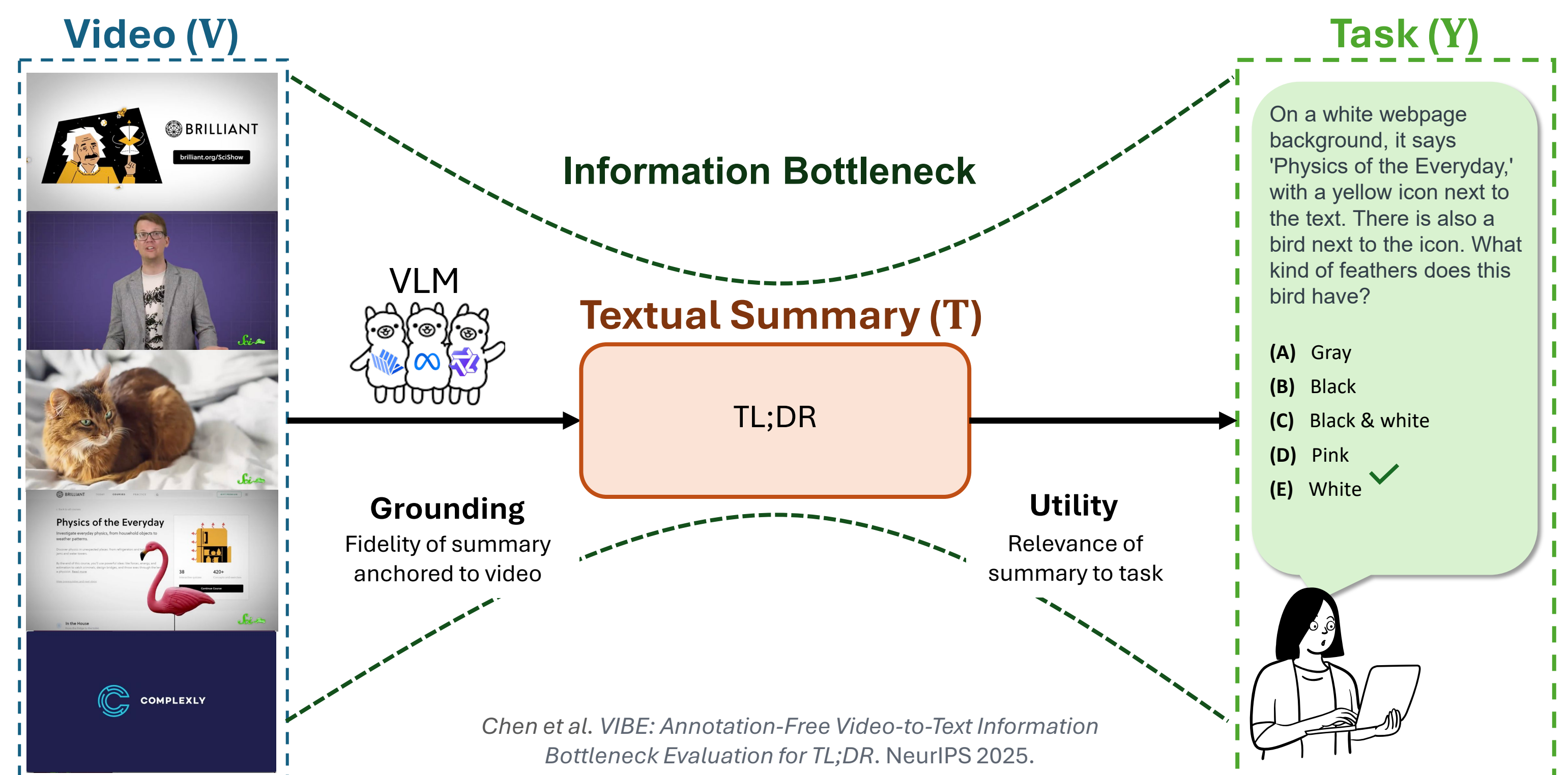
User study. With 18 graduate students (mean age = 26.28), Multi-Step-Intent achieved fewer steps and control switches, higher success rates, and lower cognitive-load ratings than both baselines.



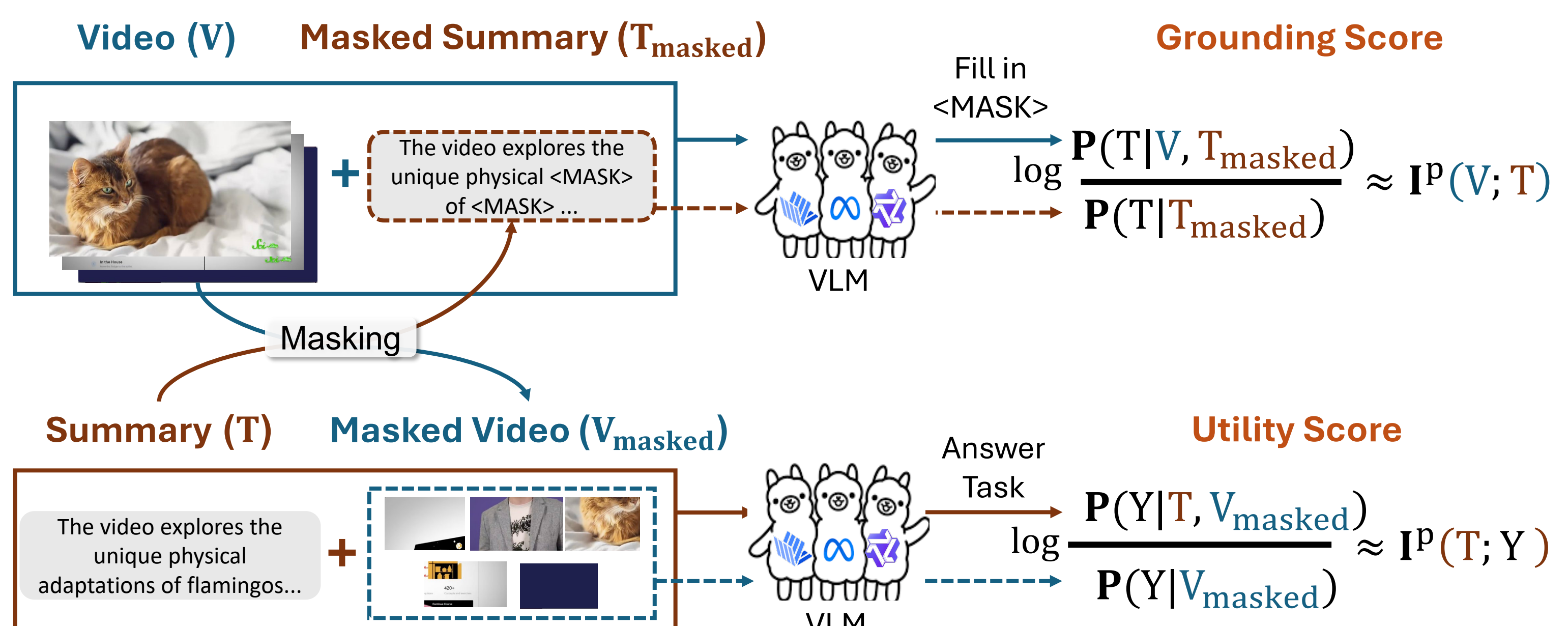
Information-theoretic Multimodal Evaluation

Problem: Manual video review slows decision-making in domains like traffic monitoring, where human oversight remains essential. Yet VLM-generated summaries are verbose and poorly aligned with downstream tasks, reducing human efficiency.

Challenge: Reference-based evaluations (e.g., ROUGE and BLEU) require **costly human annotations** and **focus on text similarities**, limiting scalability and grounding in visual information.



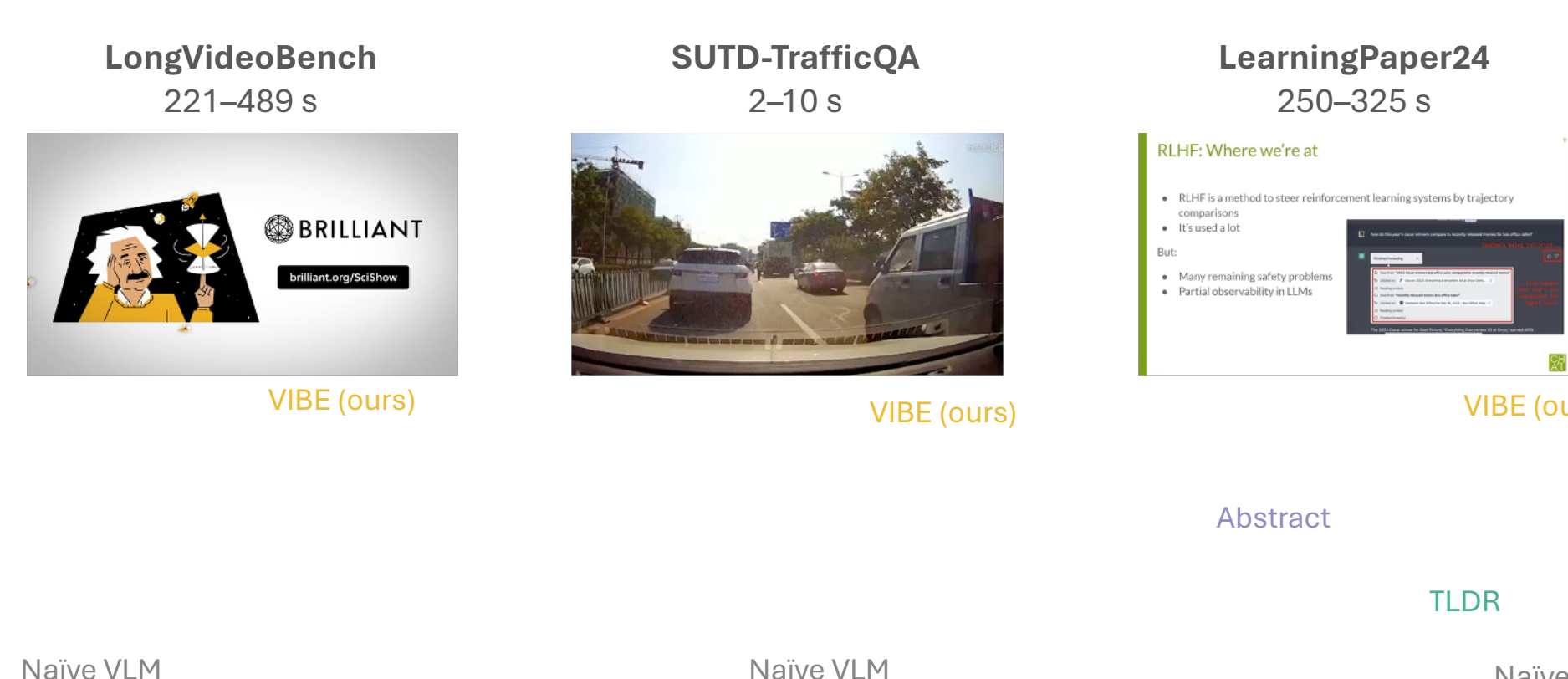
VIBE applies **Information Bottleneck** principles to evaluate textual summaries on **grounding** (video-summary alignment) and **utility** (summary-task relevance). It computes scores using multimodal masking with pointwise mutual information.



Rejection Sampling: Selects summaries that maximize a weighted sum between **grounding** and **utility** scores as optimal captions for humans.

Pareto frontier across datasets

reveals tradeoff between grounding and utility

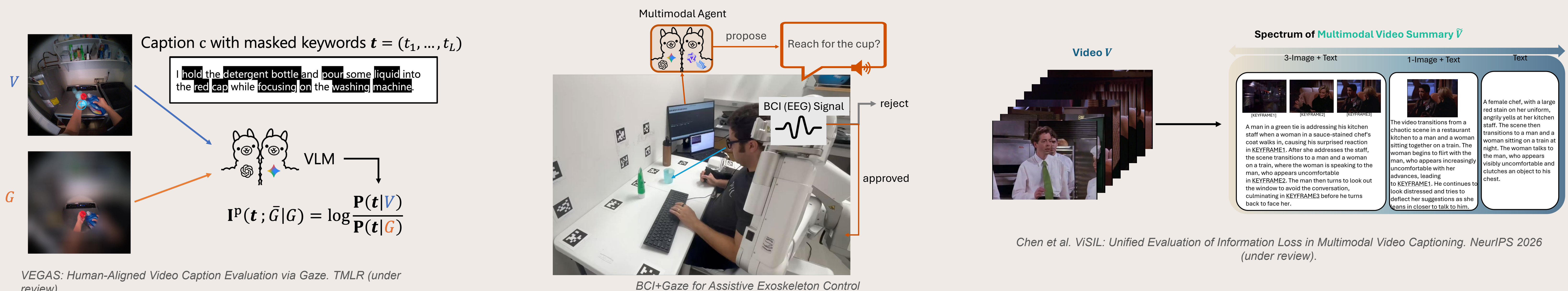


User study

Max-Utility and **Max-Grounding** summaries are **more accurate** than naive VLM outputs, with **less response time** than raw video.

Ongoing and Future Directions

To bring human *behavioral* and *physiological signals*, such as gaze and BCI, into more *embodied* interaction loop.



Organizers

